Source Coding and Compression

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Rate-Distortion Theory



Outline

Part I: Source Coding Fundamentals

- Probability, Random Variables and Random Processes
- Lossless Source Coding
- Rate-Distortion Theory
 - Operational Rate-Distortion Function
 - Information Rate-Distortion Function
 - Shannon Lower Bound
 - Rate-Distortion Function for Gaussian Sources
- Quantization
- Predictive Coding
- Transform Coding

Part II: Application in Image and Video Coding

- Still Image Coding / Intra-Picture Coding
- Hybrid Video Coding (From MPEG-2 Video to H.265/HEVC)

Rate-Distortion Theory – Motivation

Lossy coding: Decoded signal is an approximation of original

Rate-distortion theory: Information theoretical bounds for lossy compression

- Results are obtained without consideration of a specific coding method
- Goal of rate-distortion theory is to calculate the minimum transmission bit rate for a given distortion and source

Example for a rate-distortion function of a discrete iid source



Transmission System and Variables

Transmission system



- Derivation in two steps
 - Define S, S', coder/decoder, distortion D and rate R
 - Establish a functional relationship between S, S', D, and R
- For two types of random variables
 - Discrete random variables
 - Continuous-amplitude random variables (Gaussian, Laplacian, etc.)

General Structure of Lossy Source Codecs

• Encoder:

- Irreversible encoder mapping $lpha:oldsymbol{s}
 ightarrowoldsymbol{i}$
- Lossless mapping $\gamma: oldsymbol{i}
 ightarrow oldsymbol{b}$

• Decoder:

- Lossless mapping $\gamma^{-1}: oldsymbol{b}
 ightarrow oldsymbol{i}$
- Decoder mapping $eta: oldsymbol{i} o oldsymbol{s'}$



Source Codes

- A source code Q = (α, β, γ) is given by an encoder mapping α, a decoder mapping β and a lossless mapping γ
- Special case: N-dimensional block source code $Q_N = \{\alpha_N, \beta_N, \gamma_N\}$
 - Blocks of N consecutive input samples are independently coded
 - Each block of input samples $s^{(N)} = \{s_0, \cdots, s_{N-1}\}$ is mapped to a vector of K quantization indexes

$$\boldsymbol{i}^{(K)} = \alpha_N(\boldsymbol{s}^{(N)}) \tag{169}$$

• Resulting vector of indexes $m{i}^{(N)}$ is converted into a bit sequence

$$\boldsymbol{b}^{(\ell)} = \gamma_N(\boldsymbol{i}^{(K)}) = \gamma_N(\alpha_N(\boldsymbol{s}^{(N)}))$$
(170)

• At decoder side, index vector is recovered

$$i^{(K)} = \gamma_N^{-1}(b^{(\ell)}) = \gamma_N^{-1}(\gamma_N(i^{(K)}))$$
 (171)

- Index vector is mapped to a block of reconstructed samples $\pmb{s'}^{(N)} = \{s'_0, \cdots, s'_{N-1}\}$

$$\boldsymbol{s'}^{(N)} = \beta_N(\boldsymbol{i}^{(K)}) = \beta_N(\alpha_N(\boldsymbol{s}^{(N)}))$$
(172)

Distortion

• Distortion: Measure of difference between a block of N input samples $s^{(N)} = \{s_0, s_1, \dots, s_{N-1}\}$ and the corresponding block of reconstructed samples $s'^{(N)} = \{s'_0, s'_1, \dots, s'_{N-1}\}$,

$$d_N\left(oldsymbol{s}^{(N)},oldsymbol{s'}^{(N)}
ight)$$

• Typically: Additive distortion measures

$$d_N(\boldsymbol{s}^{(N)}, \boldsymbol{s'}^{(N)}) = \frac{1}{N} \sum_{i=0}^{N-1} d_1(s_i, s'_i)$$
(173)

with the single symbol distortion $d_1(s,s') \ge 0$ (equality, if and only if s = s')

• In this lecture: Mean squared error $d_1(s,s') = (s-s')^2$

$$d_N\left(\boldsymbol{s}^{(N)}, \boldsymbol{s'}^{(N)}\right) = \frac{1}{N} \sum_{i=0}^{N-1} d_1(s_i, s'_i) = \frac{1}{N} \sum_{i=0}^{N-1} (s_i - s'_i)^2$$
(174)

Average Distortion for Source Codes

• Average distortion for a stationary random process $S = \{S_n\}$ and an N-dimensional block source code $Q_N = \{\alpha_N, \beta_N, \gamma_N\}$

$$\delta(Q_N) = E\left\{d_N\left(\boldsymbol{S}^{(N)}, \beta_N(\alpha_N(\boldsymbol{S}^{(N)}))\right)\right\}$$
(175)

$$= \int_{\mathcal{R}^N} f(\boldsymbol{s}) \, d_N(\boldsymbol{s}, \, \beta_N(\alpha_N(\boldsymbol{s}))) \, \mathrm{d}\boldsymbol{s}$$
(176)

 \bullet For arbitrary random process ${\boldsymbol S} = \{S_n\}$ and arbitrary code Q

$$\delta(Q) = \lim_{N \to \infty} E\left\{ d_N\left(\boldsymbol{S}^{(N)}, \, \beta_N(\alpha_N(\boldsymbol{S}^{(N)}))\right) \right\}$$
(177)

• For additive distortion measures (such as the MSE distortion)

$$\delta(Q) = \delta(S, S') = E\{d_1(S, S')\} = \int_s \int_{s'} f_{SS'}(s, s') \, d_1(s, s') \, \mathrm{d}s \, \mathrm{d}s' \quad (178)$$

Average Rate for Source Codes

• Average number of bits per input symbol $(|\cdot|$ denotes the number of bits)

$$r_N(\boldsymbol{s}^{(N)}) = \frac{1}{N} \left| \gamma_N(\alpha_N(\boldsymbol{s}^{(N)})) \right| \quad \text{with} \quad \boldsymbol{b}^{(\ell)} = \gamma_N(\alpha_N(\boldsymbol{s}^{(N)})) \quad (179)$$

• Stationary random process $\pmb{S}=\{S_n\}$ and $N\text{-dimensional block source code }Q_N=\{\alpha_N,\beta_N,\gamma_N\}$

$$r(Q_N) = \frac{1}{N} E\left\{ \left| \gamma_N(\alpha_N(\mathbf{S}^{(N)})) \right| \right\}$$
(180)

$$= \frac{1}{N} \int_{\mathcal{R}^N} f(\boldsymbol{s}) \left| \gamma_N(\alpha_N(\boldsymbol{s})) \right| d\boldsymbol{s}$$
 (181)

• For arbitrary random process $\boldsymbol{S} = \{S_n\}$ and arbitrary code Q

$$r(Q) = \lim_{N \to \infty} \frac{1}{N} E\left\{ \left| \gamma_N(\alpha_N(\boldsymbol{S}^{(N)})) \right| \right\}$$
(182)

Operational Rate-Distortion Function

For given source S:

- $\bullet\,$ Each code Q is associated with a rate distortion point $(R,D)=(r(Q),\delta(Q))$
- A rate distortion point is achievable, if there exist a code Q such that $r(Q) \leq R$ and $\delta(Q) \leq D$
- The operational rate-distortion function R(D) and its inverse, the operational distortion-rate function D(R) are defined by



Motivation for Information Rate-Distortion Function

Operational rate-distortion function

• Defined by

$$R(D) = \inf_{Q: \, \delta(Q) \le D} r(Q) \tag{184}$$

- Specifies a fundamental performance bound for lossy source coding
- Difficulty to evaluate (minimization over all possible codes)

Information rate-distortion function

- Introduced by SHANNON in [Shannon 1948; Shannon1959]
- Obtain expression of rate-distortion bound that involves the distribution of the source using mutual information
- Show that information rate-distortion function is achievable

Mutual Information for Discrete Random Variables

• Mutual information between two discrete random variables A and B is defined by

$$I(A;B) = H(A) - H(A|B)$$
 (185)

- $\bullet\,$ Entropy H(A) is a measure of uncertainty about random variable A
- \bullet Conditional entropy H(A|B) is a measure of uncertainty about random variable A after observing random variable B
- $\bullet\,$ Mutual information is a measure for the reduction of uncertainty about $A\,$ due to the observation of $B\,$
- \implies Average amount of information that A carries about B
 - Mutual information for discrete random variables $A \in \mathcal{A}$ and $B \in \mathcal{B}$

$$I(A;B) = H(A) - H(A|B) = \sum_{a \in \mathcal{A}} \sum_{b \in \mathcal{B}} p(a,b) \log_2 \frac{p(a|b)}{p(a)}$$
(186)

Mutual Information for Discrete Random Variables

• Mutual information rewritten using Bayes' rule

$$I(A;B) = \sum_{a \in \mathcal{A}} \sum_{b \in \mathcal{B}} p(a,b) \log_2 \frac{p(a|b)}{p(a)}$$
$$= \sum_{a \in \mathcal{A}} \sum_{b \in \mathcal{B}} p(a,b) \log_2 \frac{p(a,b)}{p(a) p(b)}$$
$$= \sum_{a \in \mathcal{A}} \sum_{b \in \mathcal{B}} p(a,b) \log_2 \frac{p(b|a)}{p(b)}$$
$$= H(B) - H(B|A)$$
(187)

- $\bullet\,$ Mutual information between two random variables A and B represents the average amount of information that
 - ${\scriptstyle \bullet}$ the random variable A carries about the random variable B, or
 - ${\ensuremath{\, \bullet }}$ the random variable B carries about the random variable A

Mutual Information for Discrete Random Vectors

 $\bullet\,$ Mutual information between two random variables A and B

$$I(A; B) = H(A) - H(A|B) = H(B) - H(B|A) = \sum_{a \in \mathcal{A}} \sum_{b \in \mathcal{B}} p(a, b) \log_2 \frac{p(a, b)}{p(a) p(b)}$$
(188)

• Extension to N-dimensional random vectors $\mathbf{A} = (A_0, A_1, \cdots, A_{N-1})^T$ and $\mathbf{B} = (B_0, B_1, \cdots, B_{N-1})^T$

$$I_{N}(\boldsymbol{A};\boldsymbol{B}) = H_{N}(\boldsymbol{A}) - H_{N}(\boldsymbol{A}|\boldsymbol{B})$$

= $H_{N}(\boldsymbol{B}) - H_{N}(\boldsymbol{B}|\boldsymbol{A})$
= $\sum_{\boldsymbol{a}\in\mathcal{A}^{N}}\sum_{\boldsymbol{b}\in\mathcal{B}^{N}} p(\boldsymbol{a},\boldsymbol{b})\log_{2}\frac{p(\boldsymbol{a},\boldsymbol{b})}{p(\boldsymbol{a})p(\boldsymbol{b})}$ (189)

Properties of Mutual Information for Discrete RV

ullet Mutual information between discrete random vectors A and B

$$I_N(\boldsymbol{A};\boldsymbol{B}) = H_N(\boldsymbol{A}) - H_N(\boldsymbol{A}|\boldsymbol{B})$$
(190)

$$= H_N(\boldsymbol{B}) - H_N(\boldsymbol{B}|\boldsymbol{A})$$
(191)

• Since the conditional entropies are non-negative

$$I_N(\boldsymbol{A};\boldsymbol{B}) \leq H_N(\boldsymbol{A}) \tag{192}$$

$$I_N(\boldsymbol{A};\boldsymbol{B}) \leq H_N(\boldsymbol{B}) \tag{193}$$

ullet For independent random vectors A and B

$$I_N(\boldsymbol{A};\boldsymbol{B}) = 0 \tag{194}$$

• If the random vector B is a deterministic function of the random vector A,

$$\boldsymbol{B} = f(\boldsymbol{A}) \implies I_N(\boldsymbol{A}; \boldsymbol{B}) = H_N(\boldsymbol{B})$$
 (195)

Mutual Information for Coding of Discrete Sources

 Consider mutual information I_N(S; S') between a vector of N successive input samples S and the corresponding vector of N reconstructed samples S'

$$I_N(\boldsymbol{S}; \boldsymbol{S'}) = H_N(\boldsymbol{S'}) - H_N(\boldsymbol{S'}|\boldsymbol{S})$$

$$\leq H_N(\boldsymbol{S'})$$
(196)

where equality is achieved if and only if the vector S^\prime of reconstructed samples is a deterministic function of the input vector S

• Recall: Fundamental bound for lossless coding

$$r(Q) \ge \bar{H}(\mathbf{S'}) = \lim_{N \to \infty} \frac{H_N(\mathbf{S'})}{N}$$
(197)

 $\bullet\,$ Rate of for code Q

$$r(Q) \ge \lim_{N \to \infty} \frac{H_N(\mathbf{S'})}{N} \ge \lim_{N \to \infty} \frac{I_N(\mathbf{S'}; \mathbf{S})}{N}$$
(198)

Mutual Information for Continuous Random Variables

Remember: Discrete random variables

 $\bullet\,$ Mutual information for discrete random variables A and B

$$I(A;B) = H(A) - H(A|B)$$
(199)
= $H(B) - H(B|A)$ (200)

• For continuous random variables, the discrete entropies are not defined (they approach infinity)

Definition of mutual information for continuous random variables

- $\bullet\,$ Quantize pdfs with a quantization step size $\Delta\,$
- Calculate mutual information for resulting discrete random variables
- ${\, \bullet \, }$ Consider limit for quantization step size Δ approaching zero

Discretization of Continuous Random Variables



• Approximation $f_X^{(\Delta)}$ of pdf f_X

$$\forall x : x_i \le x < x_{i+1} \qquad f_X^{(\Delta)}(x) = \frac{1}{\Delta} \int_{x_i}^{x_{i+1}} f_X(x') \, \mathrm{d}x' \tag{201}$$

• Pmf $p_{X_{\Delta}}$ for random variable X_{Δ}

$$p_{X_{\Delta}}(x_i) = \int_{x_i}^{x_{i+1}} f_X(x') \, \mathrm{d}x' = f_X^{(\Delta)}(x_i) \cdot \Delta$$
(202)

• Joint pmf of two discrete approximations X_{Δ} and Y_{Δ}

$$p_{X_{\Delta}Y_{\Delta}}(x_i, y_j) = f_{XY}^{(\Delta)}(x_i, y_j) \cdot \Delta^2$$
(203)

Mutual Information for Continuous Random Variables

• Mutual information for discrete random variables $X_{\Delta} \in \mathcal{A}_{X_{\Delta}}$ and $Y_{\Delta} \in \mathcal{A}_{Y_{\Delta}}$

$$I(X_{\Delta}; Y_{\Delta}) = \sum_{x_i \in \mathcal{A}_{X_{\Delta}}} \sum_{y_i \in \mathcal{A}_{Y_{\Delta}}} p_{X_{\Delta}Y_{\Delta}}(x_i, y_j) \log_2 \frac{p_{X_{\Delta}Y_{\Delta}}(x_i, y_i)}{p_{X_{\Delta}}(x_i) p_{Y_{\Delta}}(y_j)}$$
(204)
$$= \sum_{x_i \in \mathcal{A}_{X_{\Delta}}} \sum_{y_i \in \mathcal{A}_{Y_{\Delta}}} f_{XY}^{(\Delta)}(x_i, y_j) \cdot \log_2 \frac{f_{XY}^{(\Delta)}(x_i, y_j)}{f_X^{(\Delta)}(x_i) f_Y^{(\Delta)}(y_j)} \cdot \Delta^2$$

• The mutual information I(X;Y) for the continuous random variables X and Y is obtained for Δ approaching zero,

$$I(X;Y) = \lim_{\Delta \to 0} I(X_{\Delta};Y_{\Delta})$$
(205)

• For $\Delta \to 0$, the piecewise constant pdf approximations $f_{XY}^{(\Delta)}$, $f_X^{(\Delta)}$, and $f_Y^{(\Delta)}$ approach the pdfs f_{XY} , f_X , and f_Y , and we obtain

$$I(X;Y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{XY}(x,y) \log_2 \frac{f_{XY}(x,y)}{f_X(x) f_Y(y)} \, \mathrm{d}x \, \mathrm{d}y$$
(206)

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Mutual Information for Continuous Random Vectors

 ${\ensuremath{\, \bullet }}$ Mutual information for continuous random variables X and Y

$$I(X;Y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{XY}(x,y) \log_2 \frac{f_{XY}(x,y)}{f_X(x) f_Y(y)} \, \mathrm{d}x \, \mathrm{d}y$$
(207)

- Consider extension to N-dimensional random vectors $\boldsymbol{X} = (X_0, X_1, \cdots, X_{N-1})^{\mathrm{T}} \text{ and } \boldsymbol{Y} = (Y_0, Y_1, \cdots, Y_{N-1})^{\mathrm{T}}$ $I_N(\boldsymbol{X}; \boldsymbol{Y}) = \int_{\mathcal{R}^N} \int_{\mathcal{R}^N} f_{\boldsymbol{X}\boldsymbol{Y}}(\boldsymbol{x}, \boldsymbol{y}) \log_2 \frac{f_{\boldsymbol{X}\boldsymbol{Y}}(\boldsymbol{x}, \boldsymbol{y})}{f_{\boldsymbol{X}}(\boldsymbol{x}) f_{\boldsymbol{Y}}(\boldsymbol{y})} \, \mathrm{d}\boldsymbol{x} \, \mathrm{d}\boldsymbol{y}$ (208)
- Using $f_{\boldsymbol{X}\boldsymbol{Y}}(\boldsymbol{x},\boldsymbol{y})=f_{\boldsymbol{X}}(\boldsymbol{x})f_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{x},\boldsymbol{y})$, we can also write

$$I_N(\boldsymbol{X};\boldsymbol{Y}) = \int_{\mathcal{R}^N} \int_{\mathcal{R}^N} f_{\boldsymbol{X}}(\boldsymbol{x}) f_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{x},\boldsymbol{y}) \log_2 \frac{f_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{x},\boldsymbol{y})}{f_{\boldsymbol{Y}}(\boldsymbol{x})} d\boldsymbol{x} d\boldsymbol{y}$$
(209)

Mutual Information between Discrete and Continuous RV

• Let $oldsymbol{Y}$ be a discrete random vector with alphabet \mathcal{A}_Y^N

$$f_{\boldsymbol{Y}}(\boldsymbol{y}) = \sum_{\boldsymbol{a} \in \mathcal{A}_{Y}^{N}} \delta(\boldsymbol{y} - \boldsymbol{a}) p_{\boldsymbol{Y}}(\boldsymbol{a})$$
(210)

$$f_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{y}|\boldsymbol{x}) = \sum_{\boldsymbol{a}\in\mathcal{A}_{Y}^{N}} \delta(\boldsymbol{y}-\boldsymbol{a}) p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x})$$
(211)

• Rewriting mutual information using above pmfs yields

$$\begin{split} I_N(\boldsymbol{X};\boldsymbol{Y}) &= \int\limits_{\mathcal{R}^N} \int\limits_{\mathcal{R}^N} f_{\boldsymbol{X}}(\boldsymbol{x}) f_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{x},\boldsymbol{y}) \log_2 \frac{f_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{x},\boldsymbol{y})}{f_{\boldsymbol{Y}}(\boldsymbol{x})} \mathrm{d}\boldsymbol{x} \, \mathrm{d}\boldsymbol{y} \\ &= \int\limits_{\mathcal{R}^N} f_{\boldsymbol{X}}(\boldsymbol{x}) \sum_{\boldsymbol{a} \in \mathcal{A}_Y^N} p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) \log_2 \frac{p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x})}{p_{\boldsymbol{Y}}(\boldsymbol{a})} \, \mathrm{d}\boldsymbol{x} \\ &= \int\limits_{\mathcal{R}^N} f_{\boldsymbol{X}}(\boldsymbol{x}) \sum_{\boldsymbol{a} \in \mathcal{A}_Y^N} p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) \left(\log_2 p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) - \log_2 p_{\boldsymbol{Y}}(\boldsymbol{a})\right) \, \mathrm{d}\boldsymbol{x} \end{split}$$

(212)

Mutual Information between Discrete and Continuous RV

• Continue reformulation of mutual information $I_N({m X};{m Y})$

$$I_{N}(\boldsymbol{X};\boldsymbol{Y}) = \int_{\mathcal{R}^{N}} f_{\boldsymbol{X}}(\boldsymbol{x}) \sum_{\boldsymbol{a} \in \mathcal{A}_{Y}^{N}} p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) \Big(\log_{2} p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) - \log_{2} p_{\boldsymbol{Y}}(\boldsymbol{a}) \Big) \, \mathrm{d}\boldsymbol{x}$$

$$= -\sum_{\boldsymbol{a} \in \mathcal{A}_{Y}^{N}} \left(\int_{\mathcal{R}^{N}} p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) f_{\boldsymbol{X}}(\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x} \right) \log_{2} p_{\boldsymbol{Y}}(\boldsymbol{a})$$

$$+ \int_{\mathcal{R}^{N}} f_{\boldsymbol{X}}(\boldsymbol{x}) \left(\sum_{\boldsymbol{a} \in \mathcal{A}_{Y}^{N}} p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) \log_{2} p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) \right) \, \mathrm{d}\boldsymbol{x}$$

$$= -\sum_{\boldsymbol{a} \in \mathcal{A}_{Y}^{N}} p_{\boldsymbol{Y}}(\boldsymbol{a}) \log_{2} p_{\boldsymbol{Y}}(\boldsymbol{a}) - \int_{\mathcal{R}^{N}} f_{\boldsymbol{X}}(\boldsymbol{x}) \, H_{N}(\boldsymbol{Y}|\boldsymbol{X}=\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x}$$

$$= H_{N}(\boldsymbol{Y}) - \int_{\mathcal{R}^{N}} f_{\boldsymbol{X}}(\boldsymbol{x}) \, H_{N}(\boldsymbol{Y}|\boldsymbol{X}=\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x}$$
(213)

Mutual Information between Discrete and Continuous RV

 $\bullet\,$ Mutual information between a discrete random vector Y and a continuous random vector X

$$I_N(\boldsymbol{X};\boldsymbol{Y}) = H_N(\boldsymbol{Y}) - \int_{\mathcal{R}^N} f_{\boldsymbol{X}}(\boldsymbol{x}) H_N(\boldsymbol{Y}|\boldsymbol{X}=\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x}$$
(214)

where $H_N(\boldsymbol{Y})$ is the entropy of the discrete random vector \boldsymbol{Y} and

$$H_N(\boldsymbol{Y}|\boldsymbol{X}=\boldsymbol{x}) = -\sum_{\boldsymbol{a}\in\mathcal{A}_Y^N} p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x}) \log_2 p_{\boldsymbol{Y}|\boldsymbol{X}}(\boldsymbol{a}|\boldsymbol{x})$$
(215)

is the conditional entropy of $oldsymbol{Y}$ given the event $\{oldsymbol{X}\!=\!oldsymbol{x}\}$

• Since the conditional entropy $H_N({m Y}|{m X}\,{=}\,{m x})$ is always nonnegative, we have

$$I_N(\boldsymbol{X};\boldsymbol{Y}) \le H_N(\boldsymbol{Y})$$
(216)

with equality if and only if $oldsymbol{Y}$ is a deterministic function of $oldsymbol{X}$

• If ${\boldsymbol X}$ and ${\boldsymbol Y}$ are independent, we have $I_N({\boldsymbol X};{\boldsymbol Y})=0$

Mutual Information for Coding of Continuous Sources

- Consider mutual information $I_N(S; S')$ between a vector of N successive input samples S and the corresponding vector of N reconstructed samples S'
- Since vectors of reconstructed samples are discrete, we can write

$$I_N(\boldsymbol{S}; \boldsymbol{S'}) = H_N(\boldsymbol{S'}) - \int_{\mathcal{R}^N} f_{\boldsymbol{S}}(\boldsymbol{s}) H_N(\boldsymbol{S'}|\boldsymbol{S}=\boldsymbol{s}) \,\mathrm{d}\boldsymbol{s} \leq H_N(\boldsymbol{S'})$$
 (217)

where equality is achieved if and only if the vector ${\bm S'}$ of reconstructed samples is a deterministic function of the input vector ${\bm S}$

 $\bullet\,$ Using the fundamental bound for lossless coding, we have for the average rate of a source code Q,

$$r(Q) \ge \lim_{N \to \infty} \frac{H_N(\mathbf{S'})}{N} \ge \lim_{N \to \infty} \frac{I_N(\mathbf{S'}; \mathbf{S})}{N}$$
(218)

 \implies Same expression as for coding of discrete sources

Description of a Source Code using a Conditional Pdf

- Statistical properties of a mapping $s'=\beta(\alpha(s))$ can be described by an N-th order conditional pdf $g_N(s'|s)$
- Example 1: Mapping $s \to s'$: $s' = \lfloor s/\Delta \rfloor \cdot \Delta$



- For N>1, $g_N({m s}'|{m s})$ are multivariate conditional pdfs
- The pdfs $g_N(s'|s)$ obtained by a deterministic mapping (codes) are a subset of the set of all conditional pmfs

Description of a Source Code using a Conditional Pdf



Distortion for a Source Code using Conditional Pdf

- Let $g_N^Q(s'|s)$ be the N-th order conditional pdf of a source code Q with $s' \in \mathcal{R}^N$ and $s \in \mathcal{R}^N$
- \bullet *N*-th order distortion

δ

$$N(g_N) = E\{d_N(\boldsymbol{S}, \boldsymbol{S'})\}$$

= $\int_{\mathcal{R}^N} \int_{\mathcal{R}^N} f_{\boldsymbol{S}\boldsymbol{S'}}(\boldsymbol{s}, \boldsymbol{s'}) \cdot d_N(\boldsymbol{s}, \boldsymbol{s'}) \, \mathrm{d}\boldsymbol{s} \, \mathrm{d}\boldsymbol{s'}$
= $\int_{\mathcal{R}^N} \int_{\mathcal{R}^N} f_{\boldsymbol{S}}(\boldsymbol{s}) \cdot g_N^Q(\boldsymbol{s'}|\boldsymbol{s}) \cdot d_N(\boldsymbol{s}, \boldsymbol{s'}) \, \mathrm{d}\boldsymbol{s} \, \mathrm{d}\boldsymbol{s'}$ (219)

• Recall: General expression for distortion $\delta(Q)$ of a source code Q

$$\delta(Q) = \lim_{N \to \infty} E\{d_N(\boldsymbol{S}, \boldsymbol{S'})\}$$
(220)

• Distortion for a source code Q can be written as

$$\delta(Q) = \lim_{N \to \infty} \delta_N(g_N^Q) \tag{221}$$

Mutual Information for a Source Code using Conditional Pdf

 $\bullet~N\mbox{-th}$ order mutual information

$$I_{N}(g_{N}) = E\left\{\log_{2} \frac{f_{\boldsymbol{S}\boldsymbol{S}'}(\boldsymbol{S},\boldsymbol{S}')}{f_{\boldsymbol{S}}(\boldsymbol{S})f_{\boldsymbol{S}'}(\boldsymbol{S}')}\right\}$$
$$= \int_{\mathcal{R}^{N}} \int_{\mathcal{R}^{N}} f_{\boldsymbol{S}\boldsymbol{S}'}(\boldsymbol{s},\boldsymbol{s}') \cdot \log_{2} \frac{f_{\boldsymbol{S}\boldsymbol{S}'}(\boldsymbol{S},\boldsymbol{S}')}{f_{\boldsymbol{S}}(\boldsymbol{S})f_{\boldsymbol{S}'}(\boldsymbol{S}')} \,\mathrm{d}\boldsymbol{s} \,\mathrm{d}\boldsymbol{s}'$$
$$= \int_{\mathcal{R}^{N}} \int_{\mathcal{R}^{N}} f_{\boldsymbol{S}}(\boldsymbol{s}) \cdot g_{N}(\boldsymbol{s}'|\boldsymbol{s}) \cdot \log_{2} \frac{g_{N}(\boldsymbol{s}'|\boldsymbol{s})}{f_{\boldsymbol{S}'}(\boldsymbol{s}')} \,\mathrm{d}\boldsymbol{s} \,\mathrm{d}\boldsymbol{s}'$$
(222)

with

$$f_{\mathbf{S'}}(\mathbf{s'}) = \int_{\mathcal{R}^N} f_{\mathbf{S}}(\mathbf{s}) \cdot g_N(\mathbf{s'}|\mathbf{s}) \,\mathrm{d}\mathbf{s}.$$
 (223)

• For a given source S, both the N-th order distortion δ_N and the N-th order mutual information I_N are completely determined by the N-th order conditional pdf $g_N^Q(s'|s)$

Information Rate-Distortion Function

- Consider any source code Q with a distortion $\delta(Q) \leq D$
- Associated rate is denoted by r(Q)
- \bullet Output S^\prime of source codec is a discrete random process
- Remember: Fundamental theorem for lossless coding

$$r(Q) \ge \bar{H}(S') = \lim_{N \to \infty} \frac{H_N(S')}{N}$$
(224)

• Using mutual information, we can write

$$r(Q) \ge \lim_{N \to \infty} \frac{H_N(S')}{N} \ge \lim_{N \to \infty} \frac{I_N(S; S')}{N} = \lim_{N \to \infty} \frac{I_N(g_N^Q)}{N}$$
(225)

 Deterministic mapping g_N^Q as given by a source code Q is a special case of a random mapping g_N

$$I_N(g_N^Q) \ge \inf_{g_N:\delta_N(g_N) \le D} I_N(g_N)$$
(226)

Information Rate-Distortion Function

• Hence, we have

$$r(Q) \ge \lim_{N \to \infty} \frac{I_N(g_N^Q)}{N} \ge \lim_{N \to \infty} \inf_{g_N : \delta_N(g_N) \le D} \frac{I_N(g_N)}{N}$$
(227)

• Information rate-distortion function

$$R^{(I)}(D) = \lim_{N \to \infty} \inf_{g_N : \delta_N(g_N) \le D} \frac{I_N(g_N)}{N}$$

(228

• Fundamental source coding theorem

$$\forall Q: \delta(Q) \le D, \quad r(Q) \ge R^{(I)}(D)$$
(229)

 $\implies \mbox{For a given maximum distortion D, the rate $r(Q)$ for each source code Q that yields a distortion $\delta(Q) \leq D$ is greater than or equal to the information rate-distortion function $R^{(I)}(D)$}$

Information vs Operational Rate-Distortion Function

- We have shown that information rate-distortion function $R^{(I)}(D)$ represents a lower bound for all source codes Q
- \implies Lower bound for operational rate-distortion function
 - It can also be shown that $R^{(I)}(D)$ is asymptotically achievable
 - For any $\epsilon > 0$, there exists a code Q with

$$\delta(Q) \le D$$
 and
 $r(Q) \le R^{(I)}(D) + \epsilon$

(see proof in [COVER and THOMAS])

- ⇒ Information rate-distortion function is equal to operational rate-distortion function
- Use the term rate-distortion function R(D) for both in the following

(Information) Distortion-Rate Function

• Fundamental source coding theorem

$$\forall Q: \delta(Q) \le D, \quad r(Q) \ge R(D)$$
(230)

with (information) rate-distortion function

$$R(D) = \lim_{N \to \infty} \inf_{g_N: \delta_N(g_N) \le D} \frac{I_N(g_N)}{N}$$
(231)

• Alternative formulation by interchanging roles of rate and distortion

$$\forall Q: r(Q) \le R, \quad \delta(Q) \ge D^{(I)}(R)$$
(232)

with (information) distortion-rate function

$$D(R) = \lim_{N \to \infty} \inf_{g_N: I_N(g_N)/N \le R} \delta_N(g_N)$$
(233)

• Distortion-rate function D(R) is inverse of rate-distortion function R(D)

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R(D) for Discrete Sources and Additive Distortion Measures

- Example of R(D) for a discrete iid source
- R(D) is a non-increasing and convex function of D



 $\bullet\,$ There exists a value $D_{\rm max}$, so that

$$\forall D \ge D_{\max} \qquad R(D) = 0 \tag{234}$$

- \implies For MSE distortion measure: D_{\max} is equal to the variance σ^2 of the source
 - Minimum rate required for lossless transmission of a discrete source is equal to the entropy rate

$$D_{\min} = 0$$
 $R(0) = \bar{H}(S)$ (235)

⇒ Fundamental bound for lossless coding: Special case of the fundamental bound for lossy coding

R(D) for Continuous Sources and Additive Distortion Meas.

• Example of R(D) for an amplitude-continuous source



- R(D) is a **non-increasing** and **convex** function of D
- $\bullet\,$ There exists a value ${\it D}_{\rm max}$, so that

$$\forall D \ge D_{\max} \qquad R(D) = 0 \tag{236}$$

 \implies For MSE distortion measure: $D_{\rm max}$ is equal to the variance σ^2 of the source

 $\bullet \ R(D)$ approaches infinity as D approaches zero

Rate-Distortion Function for IID Sources

• N-th order distortion $\delta_N(g_N)$ for additive distortion measures

$$\delta_N(g_N) = E\{d_N(\mathbf{S}, \mathbf{S'})\} = E\left\{\frac{1}{N}\sum_{i=0}^{N-1} d_1(S_i, S'_i)\right\} = E\{d_1(S, S')\}$$
$$= \int_{-\infty}^{\infty} f_S(s) \cdot g_1(s'|s) \cdot d_1(s, s') \, \mathrm{d}s = \delta_1(g)$$
(237)

 N-th order mutual information for iid sources (Note: If the source S is iid, the reconstruction S' is also iid)

$$I_{N}(g_{N}) = E\left\{\log_{2} \frac{f_{SS'}(S, S')}{f_{S}(S) f_{S'}(S')}\right\} = E\left\{\log_{2} \left(\frac{f_{SS'}(S, S')}{f_{S}(S) f_{S'}(S')}\right)^{N}\right\}$$
$$= N \cdot E\left\{\log_{2} \frac{f_{SS'}(S, S')}{f_{S}(S) f_{S'}(S')}\right\}$$
$$= N \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{S}(s) g_{1}(s'|s) \log_{2} \frac{g_{1}(s'|s)}{f_{S'}(s')} ds ds' = N \cdot I_{1}(g)$$
(238)

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Rate-Distortion Function for IID Sources

• For iid sources and additive distortion measures, we have

$$\delta_N(g_N^Q) = \delta_1(g^Q) \quad \text{and} \quad I_N(g_N^Q) = N \cdot I_1(g^Q) \quad (239)$$

• Rate-distortion function for iid sources and additive distortion measures

$$R(D) = \lim_{N \to \infty} \inf_{g_N : \delta_N(g_N) \le D} \frac{I_N(g_N)}{N} = \inf_{g_1 : \delta_1(g_1) \le D} I_1(g_1)$$
(240)

 \implies Also called first-order rate-distortion function $R_1(D)$

• Distortion-rate function for iid sources and additive distortion measures

$$D(R) = \lim_{N \to \infty} \inf_{g_N: I_N(g_N)/N \le R} \delta_N(g_N) = \inf_{g_1: I_1(g_1) \le R} \delta_1(g_1)$$
(241)

 \implies Also called first-order distortion-rate function $D_1(R)$

N-th Order Rate-Distortion Functions

 $\bullet\,$ Can define N-th order rate-distortion and distortion-rate functions

$$R_N(D) = \inf_{g_N: \, \delta_N(g_N) \le D} \frac{I_N(g_N)}{N} \tag{242}$$

$$D_N(R) = \inf_{g_N: I_N(g_N)/N \le R} \delta_N(g_N)$$
(243)

• In general, the rate-distortion and distortion-rate functions can be written as

$$R(D) = \lim_{N \to \infty} R_N(D) \quad \text{and} \quad D(R) = \lim_{N \to \infty} D_N(R) \quad (244)$$

• For iid sources and additive distortion measures, we have

$$\boxed{R(D) = R_1(D)} \quad \text{and} \quad \boxed{D(R) = D_1(R)} \quad (245)$$

Discussion of Rate-Distortion Functions

Operational rate-distortion function

$$R(D) = \inf_{Q: \, \delta(Q) \le D} r(Q) \tag{246}$$

- Minimization over all possible source codes
- Easy to define, but impossible to evaluate

Information rate-distortion function

$$R(D) = \lim_{N \to \infty} \inf_{g_N : \delta_N(g_N) \le D} \frac{I_N(g_N)}{N}$$
(247)

- Property of source: Don't need to consider all possible codes
- Still impossible to evaluate directly (minimization over all conditional pdfs)
- Numerical minimization for discrete sources: Blahut-Arimoto algorithm

How can we proceed?

- Can derive lower bound for (information) rate-distortion function
- For some sources and distortion measures (e.g., Gaussian and MSE):
 - \implies Can show that lower bound is achievable

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Source Coding and Compression

Differential Entropy

ullet Mutual information between a continuous random vector X and a continuous or discrete random vector Y

$$I(\mathbf{X}; \mathbf{Y}) = E\left\{\log_2 \frac{f_{\mathbf{X}\mathbf{Y}}(\mathbf{X}, \mathbf{Y})}{f_{\mathbf{X}}(\mathbf{X}) f_{\mathbf{Y}}(\mathbf{Y})}\right\} = E\left\{\log_2 \frac{f_{\mathbf{X}|\mathbf{Y}}(\mathbf{X}|\mathbf{Y})}{f_{\mathbf{X}}(\mathbf{X})}\right\}$$
$$= E\left\{-\log_2 f_{\mathbf{X}}(\mathbf{X})\right\} - E\left\{-\log_2 f_{\mathbf{X}|\mathbf{Y}}(\mathbf{X}|\mathbf{Y})\right\}$$
$$= h(\mathbf{X}) - h(\mathbf{X}|\mathbf{Y})$$
(248)

• Define: Differential entropy of a continuous random vector X

$$h(\boldsymbol{X}) = E\{-\log_2 f_{\boldsymbol{X}}(\boldsymbol{X})\} = -\int_{\mathcal{R}^N} f_{\boldsymbol{X}}(\boldsymbol{x}) \log_2 f_{\boldsymbol{X}}(\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x}$$
(249)

• Define: Conditional differential entropy of X given Y

$$h(\boldsymbol{X}|\boldsymbol{Y}) = E\left\{-\log_2 f_{\boldsymbol{X}|\boldsymbol{Y}}(\boldsymbol{X}|\boldsymbol{Y})\right\}$$
$$= -\int_{\mathcal{R}^N} \int_{\mathcal{R}^N} f_{\boldsymbol{X}\boldsymbol{Y}}(\boldsymbol{x},\boldsymbol{y}) \log_2 f_{\boldsymbol{X}|\boldsymbol{Y}}(\boldsymbol{x}|\boldsymbol{y}) \,\mathrm{d}\boldsymbol{x} \,\mathrm{d}\boldsymbol{y} \qquad (250)$$

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Source Coding and Compression

Example: Differential Entropy for an Uniform IID Source

• For an continuous iid source S, differential entropy is defined as

$$h(S) = E\{-\log_2 f(S)\} = -\int_{-\infty}^{\infty} f(s) \log_2 f(s) \,\mathrm{d}s$$
(251)

• h(S) for uniform distribution f(s)=1/A for $-A/2\leq s\leq A/2$

$$h(S) = -\int_{-A/2}^{A/2} \frac{1}{A} \log_2 \frac{1}{A} ds = \frac{1}{A} \log_2 A \int_{-A/2}^{A/2} ds = \log_2 A$$
(252)

• Differential entropy can become negative (in contrast to discrete entropy)



Differential Entropy for an Gaussian IID Source

• Gaussian iid process

$$f_S(s) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(s-\mu)^2}{2\sigma^2}}$$
(253)

• Differential entropy

$$h(S) = -\int_{-\infty}^{\infty} f_S(s) \log_2 f_S(s) ds$$

= $-\int_{-\infty}^{\infty} f_S(s) \left[-\frac{(s-\mu)^2}{2\sigma^2} \log_2 e - \log_2 \sqrt{2\pi\sigma^2} \right] ds$
= $\frac{E\{(S-\mu)^2\}}{2\sigma^2} \cdot \log_2 e + \frac{1}{2} \log_2(2\pi\sigma^2)$
= $\frac{1}{2} \log_2 e + \frac{1}{2} \log_2(2\pi\sigma^2)$
= $\frac{1}{2} \log_2(2\pi e \sigma^2)$

(254)

N-th Order Differential Entropy

• N-th order differential entropy

$$h_N(\mathbf{S}) = h(\mathbf{S}^{(N)}) = h(S_0, \cdots, S_{N-1}) = E\left\{-\log_2 f_{\mathbf{S}}(\mathbf{S}^{(N)})\right\}$$
 (255)

• Differential entropy rate

$$\bar{h}(\boldsymbol{S}) = \lim_{N \to \infty} \frac{h_N(\boldsymbol{S})}{N} = \lim_{N \to \infty} \frac{h(S_0, \cdots, S_{N-1})}{N}$$
(256)

 $\bullet~N\text{-th}$ order pdf of a stationary Gaussian process

$$f_G(\boldsymbol{s}) = \frac{1}{(2\pi)^{N/2} |\boldsymbol{C}_N|^{1/2}} e^{-\frac{1}{2} (\boldsymbol{s} - \boldsymbol{\mu}_N)^T \boldsymbol{C}_N^{-1} (\boldsymbol{s} - \boldsymbol{\mu}_N)}$$
(257)

• N-th order differential entropy of stationary Gaussian process

$$h_N^{(G)}(\mathbf{S}) = -\int_{\mathcal{R}^N} f_G(\mathbf{s}) \log_2 f_G(\mathbf{s}) d\mathbf{s}$$

= $\frac{1}{2} \log_2((2\pi)^N |\mathbf{C}_N|)$
+ $\frac{\log_2 e}{2} \int_{\mathcal{R}^N} f_G(\mathbf{s}) (\mathbf{s} - \mathbf{\mu}_N)^T \mathbf{C}_N^{-1} (\mathbf{s} - \mathbf{\mu}_N) d\mathbf{s}$ (258)

N-th order Differential Entropy of Stationary Gaussian Process

• General stationary process with pdf $f_{m{S}}(s)$, mean μ_N , covariance matrix C_N

$$f_{R^{N}} f_{S}(s) (s - \mu_{N})^{T} C_{N}^{-1} (s - \mu_{N}) ds$$

$$= E\{(S - \mu_{N})^{T} C_{N}^{-1} (S - \mu_{N})\}$$

$$= E\{\sum_{i=0}^{N-1} \sum_{j=0}^{N-1} (S_{i} - \mu_{i}) (C^{-1})_{i,j} (S_{j} - \mu_{j})\}$$

$$= \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} E\{(S_{i} - \mu_{i}) (S_{j} - \mu_{j})\} (C^{-1})_{i,j}$$

$$= \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} C_{j,i} (C^{-1})_{i,j}$$

$$= \sum_{i=0}^{N-1} (CC^{-1})_{j,j}$$

$$= N$$
(259)

N-th order Differential Entropy of Stationary Gaussian Process

 \bullet Showed for general pdf $f_{\boldsymbol{S}}(\boldsymbol{s})$

$$\int_{\mathcal{R}^N} f_{\boldsymbol{S}}(\boldsymbol{s}) \, (\boldsymbol{s} - \boldsymbol{\mu}_N)^T \boldsymbol{C}_N^{-1} (\boldsymbol{s} - \boldsymbol{\mu}_N) \, \mathrm{d}\boldsymbol{s} = N$$
(260)

• Continue derivation for stationary Gaussian source

$$h_{N}^{(G)}(\boldsymbol{S}) = \frac{1}{2} \log_{2} \left((2\pi)^{N} |\boldsymbol{C}_{N}| \right) + \frac{\log_{2} e}{2} \int_{\mathcal{R}^{N}} f_{G}(\boldsymbol{s}) (\boldsymbol{s} - \boldsymbol{\mu}_{N})^{T} \boldsymbol{C}_{N}^{-1} (\boldsymbol{s} - \boldsymbol{\mu}_{N}) \, \mathrm{d}\boldsymbol{s} = \frac{1}{2} \log_{2} \left((2\pi)^{N} |\boldsymbol{C}_{N}| \right) + \frac{N}{2} \log_{2} e = \frac{1}{2} \log_{2} \left((2\pi)^{N} |\boldsymbol{C}_{N}| \right) + \frac{1}{2} \log_{2} e^{N} = \frac{1}{2} \log_{2} \left((2\pi e)^{N} |\boldsymbol{C}_{N}| \right)$$
(261)

N-th order Differential Entropy of Stat. Non-Gaussian Process

- ullet Consider stationary non-Gaussian process with N-th order pdf f(s)
- Let $f_G(s)$ be the N-th order pdf of a Gaussian process with the same N-th order autocovariance matrix C_N
- By applying the divergence inequality for pdfs, we obtain

$$\begin{aligned} h_N(\boldsymbol{S}) &= -\int_{\mathcal{R}^N} f(\boldsymbol{s}) \log_2 f(\boldsymbol{s}) \, \mathrm{d}\boldsymbol{s} \\ &\leq -\int_{\mathcal{R}^N} f(\boldsymbol{s}) \log_2 f_G(\boldsymbol{s}) \, \mathrm{d}\boldsymbol{s} \\ &= \frac{1}{2} \log_2 \left((2\pi)^N |\boldsymbol{C}_N| \right) + \frac{\log_2 e}{2} \int_{\mathcal{R}^N} f(\boldsymbol{s}) (\boldsymbol{s} - \boldsymbol{\mu}_N)^T \boldsymbol{C}_N^{-1} (\boldsymbol{s} - \boldsymbol{\mu}_N) \, \mathrm{d}\boldsymbol{s} \\ &= \frac{1}{2} \log_2 \left((2\pi e)^N |\boldsymbol{C}_N| \right) = h_N^{(G)}(\boldsymbol{S}) \end{aligned}$$
(262)

 \implies Gaussian process with a given *N*-th order autocovariance matrix C_N has the largest *N*-th order differential entropy among all processes with the same autocovariance matrix C_N

1

Eigendecomposition of the Covariance Matrix

• Determinant $|C_N|$: Product of the eigenvalues ξ_i of the matrix C_N ,

$$\boldsymbol{C}_{N} = \boldsymbol{A}_{N} \boldsymbol{\Xi}_{N} \boldsymbol{A}_{N}^{T} \quad \rightarrow \quad |\boldsymbol{C}_{N}| = \underbrace{|\boldsymbol{A}_{N}|}_{=1} \cdot |\boldsymbol{\Xi}_{N}| \cdot \underbrace{|\boldsymbol{A}_{N}^{T}|}_{=1} = \prod_{i=0}^{N-1} \xi_{i}^{(N)} \quad (263)$$

• A_N : Orthogonal matrix with the N unit-norm eigenvectors as columns

$$\boldsymbol{A}_{N} = \left(\boldsymbol{v}_{0}^{(N)}, \boldsymbol{v}_{1}^{(N)}, \cdots, \boldsymbol{v}_{N-1}^{(N)} \right)$$
(264)

• Ξ_N : Diagonal matrix with the N eigenvalues of C_N on its main diagonal

$$\boldsymbol{\Xi}_{N} = \begin{pmatrix} \xi_{0}^{(N)} & 0 & \dots & 0\\ 0 & \xi_{1}^{(N)} & \dots & 0\\ \vdots & \vdots & \ddots & 0\\ 0 & 0 & 0 & \xi_{N-1}^{(N)} \end{pmatrix}$$
(265)

Maximum Differential Entropy

• Determinant of a matrix is the product of its eigenvalues

$$|\boldsymbol{C}_{N}| = \prod_{i=0}^{N-1} \xi_{i}^{(N)}$$
(266)

• Trace of a matrix is the sum of its eigenvalues (trace is similarity invariant)

$$\operatorname{tr}(|\boldsymbol{C}_{N}|) = \sum_{i=0}^{N-1} \xi_{i}^{(N)} = N \cdot \sigma^{2}$$
(267)

• Inequality of arithmetic and geometric means:

$$\left(\prod_{i=0}^{N-1} x_i\right)^{\frac{1}{N}} \le \frac{1}{N} \sum_{i=0}^{N-1} x_i,$$
(268)

with equality if and only if $x_0 = x_1 = \ldots = x_{N-1}$ (when geometric mean is maximized)

Maximum Differential Entropy

• Apply inequality to determinant of autocovariance matrix

$$|C_N| = \prod_{i=0}^{N-1} \xi_i \le \left(\frac{1}{N} \sum_{i=0}^{N-1} \xi_i\right)^N = \sigma^{2N}$$
(269)

 \implies Equality if and only if source is iid (all eigenvalues are the same)

 $\bullet\,$ For N-th order differential entropy of any source ${\boldsymbol S}$, we get

$$\begin{split} h_N(\boldsymbol{S}) &\leq \frac{1}{2} \log_2 \left((2\pi e)^N |\boldsymbol{C}_N| \right) & \text{(equality for Gaussian)} \\ &\leq \frac{N}{2} \log_2 \left(2\pi e \sigma^2 \right) & \text{(equality for iid)} \end{split}$$
(270)

 \implies Equality if and only if source is Gaussian iid

 \implies For a given variance σ^2 , the *N*-th order differential entropy is maximized for Gaussian iid processes

$$h_N(\mathbf{S}) \le \frac{N}{2}\log_2\left(2\pi e\sigma^2\right)$$

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Source Coding and Compression

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Shannon Lower Bound

• Lower bound for rate-distortion function R(D)

$$R(D) = \lim_{N \to \infty} \inf_{g_N: \delta_N(g_N) \le D} \frac{I_N(\boldsymbol{S}; \boldsymbol{S'})}{N}$$

=
$$\lim_{N \to \infty} \inf_{g_N: \delta_N(g_N) \le D} \frac{h_N(\boldsymbol{S}) - h_N(\boldsymbol{S}|\boldsymbol{S'})}{N}$$

=
$$\lim_{N \to \infty} \frac{h_N(\boldsymbol{S})}{N} - \lim_{N \to \infty} \sup_{g_N: \delta_N(g_N) \le D} \frac{h_N(\boldsymbol{S}|\boldsymbol{S'})}{N}$$

=
$$\bar{h}(\boldsymbol{S}) - \lim_{N \to \infty} \sup_{g_N: \delta_N(g_N) \le D} \frac{h_N(\boldsymbol{S} - \boldsymbol{S'}|\boldsymbol{S'})}{N}$$
(272)

• Define: Shannon Lower Bound

$$R_L(D) = \bar{h}(\boldsymbol{S}) - \lim_{N \to \infty} \sup_{g_N: \, \delta_N(g_N) \le D} \frac{h_N(\boldsymbol{S} - \boldsymbol{S'})}{N}$$
(273)

• Since conditioning does not increase differential entropy, we have

$$R(D) \ge R_L(D)$$
 (equality if $S - S'$ is independent of S') (274)

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Source Coding and Compression

Shannon Lower Bound for MSE Distortion

• For MSE distortion: Distortion is given by variance of differences

$$\delta_N(g_N)=\sigma_Z^2$$
 with $oldsymbol{Z}=oldsymbol{S}-oldsymbol{S'}$ and $\mu_Z=0$ (275)

• Remember: Maximum differential entropy

$$h_N(S - S') = h_N(Z) \le \frac{N}{2} \log_2(2\pi e \sigma_Z^2) = \frac{N}{2} \log_2(2\pi e D)$$
 (276)

• Shannon lower bound for MSE distortion

$$R_L(D) = \bar{h}(\boldsymbol{S}) - \frac{1}{2}\log_2\left(2\pi eD\right)$$
(277)

 \implies For given C_N or $\Phi_{SS}(\omega)$, maximized for Gaussian processes \implies For given σ^2 , maximized for Gaussian iid processes

• When is the Shannon lower bound for MSE achievable?

 \implies Difference process $oldsymbol{Z} = oldsymbol{S} - oldsymbol{S}'$ has to be zero-mean Gaussian iid

 \implies Difference process Z = S - S' has to be independent of S':

$$g_{\boldsymbol{Z}|\boldsymbol{S'}}(\boldsymbol{z}|\boldsymbol{s'}) = g_{\boldsymbol{Z}}(\boldsymbol{z})$$

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Shannon Lower Bound for IID Sources MSE Distortion

• Shannon lower bound for MSE distortion

$$R_L(D) = \bar{h}(\mathbf{S}) - \frac{1}{2}\log_2(2\pi eD) \qquad \qquad D_L(R) = \frac{1}{2\pi e} \cdot 2^{2\bar{h}(\mathbf{S})} \cdot 2^{-2R}$$
(278)

ullet For iid sources $oldsymbol{S}$, we have

$$\bar{h}(\mathbf{S}) = \lim_{N \to \infty} \frac{h_N(\mathbf{S})}{N} = \lim_{N \to \infty} \frac{1}{N} E\{-\log_2 f_{\mathbf{S}}(\mathbf{S})\} = \lim_{N \to \infty} \frac{1}{N} \sum_{i=0}^{N-1} E\{-\log_2 f_S(S_i)\} = \lim_{N \to \infty} \frac{N}{N} E\{-\log_2 f_S(S)\} = E\{-\log_2 f_S(S)\} = h(S)$$
(279)

• Shannon lower bound for MSE distortion and iid sources

$$R_L(D) = h(S) - \frac{1}{2}\log_2(2\pi eD) \qquad \qquad D_L(R) = \frac{1}{2\pi e} \cdot 2^{2h(S)} \cdot 2^{-2R}$$
(280)

Shannon Lower Bound Selected IID Sources

• Uniform pdf:

$$h(S) = \frac{1}{2}\log_2(12\sigma^2) \implies D_L(R) = \underbrace{\frac{6}{\pi e}}_{\approx 0.7} \sigma^2 \cdot 2^{-2R}$$

• Laplacian pdf:

$$h(S) = \frac{1}{2} \log_2(2e^2 \sigma^2) \implies D_L(R) = \underbrace{\frac{e}{\pi}}_{\approx 0.865} \sigma^2 \cdot 2^{-2R}$$

(281)

• Gaussian pdf:

$$h(S) = \frac{1}{2}\log_2(2\pi e\sigma^2) \implies D_L(R) = \sigma^2 \cdot 2^{-2R}$$

Shannon Lower Bound Selected IID Sources

Shannon lower bound using MSE and SNR

$$\mathrm{SNR} = 10 \log_{10} \frac{\sigma^2}{\mathrm{MSE}}$$

(284)

- Uniform iid process: red
- Laplace iid process: green
- Gauss iid process: blue



Asymptotic Tightness of the Shannon Lower Bound

• Shannon lower bound approaches distortion rate function for small distortions or high rates

$$\lim_{D \to 0} R(D) - R_L(D) = 0.$$
 (285)

• Comparison of D(R) with $D_L(R)$ for the Laplacian iid source

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Shannon Lower Bound for Gaussian Sources with Memory

• Differential entropy for Gaussian sources

$$h_N^{(G)}(\mathbf{S}) = \frac{1}{2} \log_2((2\pi e)^N |\mathbf{C}_N|)$$
 (286)

• Shannon lower bound for MSE distortion

$$R_{L}(D) = \lim_{N \to \infty} \frac{h_{N}^{(G)}(\mathbf{S})}{N} - \frac{1}{2} \log_{2}(2\pi eD)$$

$$= \lim_{N \to \infty} \frac{\log_{2}((2\pi e)^{N} |\mathbf{C}_{N}|)}{2N} - \frac{1}{2} \log_{2}(2\pi eD)$$

$$= \frac{1}{2} \log_{2}(2\pi e) + \lim_{N \to \infty} \frac{\log_{2}(|\mathbf{C}_{N}|)}{2N} - \frac{1}{2} \log_{2}(2\pi eD)$$

$$= \lim_{N \to \infty} \frac{\log_{2}|\mathbf{C}_{N}|}{2N} - \frac{1}{2} \log_{2}D$$

$$= \lim_{N \to \infty} \frac{1}{2N} \sum_{i=0}^{N-1} \log_{2} \xi_{i}^{(N)} - \frac{1}{2} \log_{2}D \qquad (287)$$

GRENANDER and SZEGÖ's theorem

- Assume zero-mean process: $oldsymbol{C}_N = oldsymbol{R}_N$
- Given the conditions
 - \mathbf{R}_N is a sequence of Hermitian Toeplitz matrices with elements ϕ_k on the k-th diagonal
 - The infimum $\Phi_{inf} = inf_{\omega} \Phi(\omega)$ and supremum $\Phi_{sup} = sup_{\omega} \Phi(\omega)$ of the Fourier series are finite

$$\Phi(\omega) = \sum_{k=-\infty}^{\infty} \phi_k \, e^{-j\omega k} \tag{288}$$

- The function ${\it G}$ is continuous in the interval $[\Phi_{\rm inf}, \Phi_{\rm sup}]$
- The following expression holds

$$\lim_{N \to \infty} \frac{1}{N} \sum_{i=0}^{N-1} G\left(\xi_i^{(N)}\right) = \frac{1}{2\pi} \int_{-\pi}^{\pi} G\left(\Phi(\omega)\right) \,\mathrm{d}\omega$$
(289)

where $\xi_i^{(N)}$, for $i=0,1,\ldots,N-1$, denote the eigenvalues of the N-th matrix ${\pmb R}_{\!N}$

Shannon Lower Bound

Shannon Lower Bound for Gaussian Sources with Memory

• We have already derived

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$$R_L(D) = \lim_{N \to \infty} \frac{1}{2N} \sum_{i=0}^{N-1} \log_2 \xi_i^{(N)} - \frac{1}{2} \log_2 D$$
(290)

• Applying GRENANDER and SZEGÖ's theorem

$$\lim_{N \to \infty} \frac{1}{N} \sum_{i=0}^{N-1} G\left(\xi_i^{(N)}\right) = \frac{1}{2\pi} \int_{-\pi}^{\pi} G\left(\Phi(\omega)\right) \,\mathrm{d}\omega$$
(291)

yields

$$R_L(D) = \frac{1}{4\pi} \int_{-\pi}^{\pi} \log_2 \Phi_{SS}(\omega) \, d\omega - \frac{1}{2} \log_2 D$$
$$= \frac{1}{4\pi} \int_{-\pi}^{\pi} \log_2 \Phi_{SS}(\omega) \, d\omega - \frac{1}{4\pi} \log_2 D \int_{-\pi}^{\pi} d\omega$$
$$= \frac{1}{4\pi} \int_{-\pi}^{\pi} \log_2 \frac{\Phi_{SS}(\omega)}{D} \, d\omega$$
(292)

Power Spectral Density of a Gauss-Markov Process

• Zero-mean Gauss-Markov process with $|\rho| < 1$

$$S_n = Z_n + \rho \cdot S_{n-1} \tag{293}$$

Auto-correlation function

$$\phi[k] = \sigma^2 \cdot \rho^{|k|} \tag{294}$$

• Using the relationship

$$\sum_{k=1}^{\infty} a^k e^{-jkx} = \frac{a}{e^{-jx} - a}$$
(295)

we obtain

$$\Phi_{SS}(\omega) = \sum_{k=-\infty}^{\infty} \phi[k] \cdot e^{-j\omega k}$$

$$= \sum_{k=-\infty}^{\infty} \sigma^2 \cdot \rho^{|k|} \cdot e^{-j\omega k}$$

$$= \sigma^2 \cdot \left(1 + \frac{\rho}{e^{-j\omega} - \rho} + \frac{\rho}{e^{j\omega} - \rho}\right)$$

$$= \sigma^2 \cdot \frac{1 - \rho^2}{1 - 2\rho \cos \omega + \rho^2}$$
Source Coding and Compression
(296)

Heiko Schwarz

Source Coding and Compression

Shannon Lower Bound for Gaussian-Markov Processes

• Shannon lower bound for a zero-mean Gauss-Markov process with |
ho| < 1

$$R_{L}(D) = \frac{1}{4\pi} \int_{-\pi}^{\pi} \log_{2} \frac{\Phi_{SS}(\omega)}{D} d\omega$$

$$= \frac{1}{4\pi} \int_{-\pi}^{\pi} \log_{2} \frac{\sigma^{2}(1-\rho^{2})}{D} d\omega - \frac{1}{4\pi} \underbrace{\int_{-\pi}^{\pi} \log_{2}(1-2\rho\cos\omega+\rho^{2}) d\omega}_{=0}$$

$$R_{L}(D) = \frac{1}{2} \log_{2} \frac{\sigma^{2}(1-\rho^{2})}{D}$$
(297)

where we used

$$\int_0^{\pi} \ln(a^2 - 2ab\cos x + b^2) \,\mathrm{d}x = 2\pi \ln a \tag{298}$$

• Shannon lower bound as distortion-rate function

$$D_L(R) = (1 - \rho^2) \,\sigma^2 \, 2^{-2R}$$
(299)

• Consider Gaussian iid source

$$f_S(s) = \frac{1}{2\pi\sigma^2} e^{-\frac{(s-\mu)^2}{2\sigma^2}}$$
(300)

• Shannon lower bound for Gaussian iid sources

$$\overline{D_L(R) = \sigma^2 \cdot 2^{-2R}} \iff \begin{array}{ccc} R_L(D) = \begin{cases} \frac{1}{2} \log_2 \frac{\sigma^2}{D} & : D \le \sigma^2 \\ 0 & : D > \sigma^2 \end{cases}$$
(301)

- For Gaussian iid sources: Rate-distortion function = Shannon lower bound
- How can we proof it?
 - · Could show that Shannon lower bound is achievable
 - \implies Need to find $g_{S'|S}(s'|s)$ for which the Shannon lower bound is achieved
- Remember: Discussed that Shannon lower bound is achievable if
 - Difference signal Z = S S' is independent of S'
 - Difference signal Z = S S' has a zero-mean Gaussian distribution

Consider conditional pdf $g_{Z|S'}(z|s') = g_{S-S'|S'}(s-s'|s')$ instead of $g_{S'|S}(s'|s)$

 $\bullet\,$ Given $g_{Z|S'}(z|s'),$ conditional pdf $g_{S'|S}(s'|s)$ can be derived by

$$g_{S'|S}(s'|s) = g_{S|S'}(s|s') \cdot \frac{f_{S'}(s')}{f_S(s)} \quad \text{with} \quad g_{S|S'}(s|s') = g_{Z|S'}(z+s'|s')$$
(302)

- Shannon lower bound coincides with rate-distortion function, only if the difference signal Z = S S' fulfills the conditions:
 - Difference signal $Z=S-S^\prime$ is independent of S^\prime
 - Difference signal Z = S S' has a zero-mean Gaussian distribution
- $\bullet\,$ Hence, $g_{Z|S'}(z|s')$ has to have the form

$$g_{Z|S'}(z|s') = \frac{1}{\sqrt{2\pi\sigma_Z^2}} e^{-\frac{z^2}{2\sigma_Z^2}} = \frac{1}{\sqrt{2\pi D}} e^{-\frac{z^2}{2D}} = f_Z(z)$$
(303)

• Need to verify that this is a valid choice!

• Question: Is the conditional pdf $g_{Z|S'}(z|s')$ a valid choice?

$$g_{Z|S'}(z|s') = f_Z(z) = \frac{1}{\sqrt{2\pi D}} e^{-\frac{z^2}{2D}}$$
 (304)

- $\bullet\,$ Source S is the sum of two independent random variables Z=S-S' and S'
- Hence, $f_S(s)$ is given by the convolution

$$f_S(s) = f_Z(z) * f_{S'}(s')$$
(305)

- Note: Convolution of two Gaussians $f(\mu_1, \sigma_1^2)$ and $f(\mu_2, \sigma_2^2)$ is a Gaussian with $\mu = \mu_1 + \mu_2$ and $\sigma = \sigma_1^2 + \sigma_2^2$
- Hence, the pdf of the reconstructed samples is

$$f_{S'}(s') = \frac{1}{\sqrt{2\pi \left(\sigma^2 - D\right)}} e^{-\frac{(s' - \mu)^2}{2(\sigma^2 - D)}}$$
(306)

- This is a valid pdf for S^\prime (no negative values)
- \implies Our choice for $g_{Z|S'}(z|s')$ is valid

Check distortion and rate (mutual information)

 \bullet Distortion given by variance of difference process $Z=S-S^\prime$

$$\delta(g) = E\{(S - S')^2\} = E\{Z^2\} = D$$
(307)

Mutual information

$$I(g) = h(S) - h(S|S')$$

= $h(S) - h(S - S'|S')$
= $h(S) - h(Z|S')$
= $h(S) - h(Z)$
= $\frac{1}{2}\log_2(2\pi e\sigma^2) - \frac{1}{2}\log_2(2\pi eD)$
= $R(D) = \frac{1}{2}\log_2\frac{\sigma^2}{D}$ (308)

 \implies For Gaussian iid processes and MSE distortion, the rate-distortion function coincides with the Shannon lower bound

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Source Coding and Compression

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- \bullet Considered Gaussian iid source with a variance σ^2 and MSE distortion
- Shannon lower bound coincides with the rate-distortion function
- The rate-distortion function R(D) is given by

$$R(D) = \begin{cases} \frac{1}{2} \log_2 \frac{\sigma^2}{D}, & 0 \le D \le \sigma^2\\ 0, & D > \sigma^2 \end{cases}$$
(309)

• The distortion-rate function is given as

$$D(R) = \sigma^2 \cdot 2^{-2R} \tag{310}$$

• The signal-to-noise ratio (SNR) is given as

SNR(R) =
$$10 \cdot \log_{10} \frac{\sigma^2}{D(R)} = 10 \cdot \log_{10} 2^{2R} \approx 6R \quad [dB]$$
 (311)

For MSE distortion and a given variance σ², the rate-distortion function R(D) is maximized for Gaussian iid processes
 ⇒ Gaussian iid processes are the hardest to code

Rate-Distortion Function for Gaussian Sources with Memory

 $\bullet~N\mbox{-th}$ order pdf of stationary Gaussian random process

$$f_{\boldsymbol{S}}^{(G)}(\boldsymbol{s}) = \frac{1}{(2\pi)^{N/2} |\boldsymbol{C}_N|^{1/2}} e^{-\frac{1}{2}(\boldsymbol{s} - \boldsymbol{\mu}_N)^T \boldsymbol{C}_N^{-1}(\boldsymbol{s} - \boldsymbol{\mu}_N)}$$
(312)

• Eigendecomposition of covariance matrix C_N ,

$$\boldsymbol{C}_N = \boldsymbol{A}_N \cdot \boldsymbol{\Xi}_N \cdot \boldsymbol{A}_N^T \tag{313}$$

• A_N : Matrix with columns are equal to the N unit-norm eigenvectors

$$\boldsymbol{A}_{N} = \left(\boldsymbol{v}_{0}^{(N)}, \boldsymbol{v}_{1}^{(N)}, \cdots, \boldsymbol{v}_{N-1}^{(N)} \right)$$
(314)

• Ξ_N : Diagonal matrix with eigenvalues of C_N on its main diagonal

$$\boldsymbol{\Xi}_{N} = \begin{pmatrix} \xi_{0}^{(N)} & 0 & \dots & 0 \\ 0 & \xi_{1}^{(N)} & \dots & 0 \\ \vdots & \vdots & \ddots & 0 \\ 0 & 0 & 0 & \xi_{N-1}^{(N)} \end{pmatrix}$$
(315)

Signal Space Rotation

• Given stationary Gaussian source $\{S_n\}$: Construct source $\{U_n\}$ by decomposing $\{S_n\}$ into vectors S of size N and applying the transform

$$\boldsymbol{U} = \boldsymbol{A}_{N}^{-1} \left(\boldsymbol{S} - \boldsymbol{\mu}_{N} \right) = \boldsymbol{A}_{N}^{T} \left(\boldsymbol{S} - \boldsymbol{\mu}_{N} \right)$$
(316)

• Linear transformation of a Gaussian random vector results in another Gaussian random vector

• The chosen transform yields independent random variables U_i

$$f_{U}(\boldsymbol{u}) = \frac{1}{(2\pi)^{N/2} |\boldsymbol{\Xi}_{N}|^{1/2}} e^{-\frac{1}{2}\boldsymbol{u}^{T} \boldsymbol{\Xi}_{N}^{-1} \boldsymbol{u}} = \prod_{i=0}^{N-1} \frac{1}{\sqrt{2\pi\xi_{i}^{(N)}}} e^{-\frac{u_{i}^{2}}{2\xi_{i}^{(N)}}}$$
(317)

Mean

$$E\{\boldsymbol{U}\} = \boldsymbol{A}_{N}^{T} \left(E\{\boldsymbol{S}\} - \boldsymbol{\mu}_{N} \right) = \boldsymbol{A}_{N}^{T} \left(\boldsymbol{\mu}_{N} - \boldsymbol{\mu}_{N} \right) = \boldsymbol{0}$$
(318)

Covariance

$$E\left\{\boldsymbol{U}\boldsymbol{U}^{T}\right\} = \boldsymbol{A}_{N}^{T} E\left\{\left(\boldsymbol{S}-\boldsymbol{\mu}_{N}\right)\left(\boldsymbol{S}-\boldsymbol{\mu}_{N}\right)^{T}\right\} \boldsymbol{A}_{N}$$
$$= \boldsymbol{A}_{N}^{T} \boldsymbol{C}_{N} \boldsymbol{A}_{N} = \boldsymbol{\Xi}_{N}$$
(319)

Distortion and Mutual Information

• Inverse transform after compression identical to forward transform

$$S' = A_N U' + \mu_N, \qquad (320)$$

With

$$(\boldsymbol{U'}-\boldsymbol{U}) = \boldsymbol{A}_N^T (\boldsymbol{S'}-\boldsymbol{S}) \quad \Longleftrightarrow \quad (\boldsymbol{S'}-\boldsymbol{S}) = \boldsymbol{A}_N (\boldsymbol{U'}-\boldsymbol{U}) \quad (321)$$

ullet MSE distortion between any realization s of S and its reconstruction s'

$$d_{N}(\boldsymbol{s}; \boldsymbol{s'}) = \frac{1}{N} \sum_{i=0}^{N-1} (s_{i} - s_{i}')^{2} = \frac{1}{N} (\boldsymbol{s} - \boldsymbol{s'})^{T} (\boldsymbol{s} - \boldsymbol{s'})$$
$$= \frac{1}{N} (\boldsymbol{u} - \boldsymbol{u'})^{T} \boldsymbol{A}_{N}^{T} \boldsymbol{A}_{N} (\boldsymbol{u} - \boldsymbol{u'}) = \frac{1}{N} (\boldsymbol{u} - \boldsymbol{u'})^{T} (\boldsymbol{u} - \boldsymbol{u'})$$
$$= \frac{1}{N} \sum_{i=0}^{N-1} (u_{i} - u_{i}')^{2} = d_{N}(\boldsymbol{u}; \boldsymbol{u'})$$
(322)

• Since coordinate transform is invertible,

$$I_N(\boldsymbol{S};\boldsymbol{S'}) = I_N(\boldsymbol{U};\boldsymbol{U'}) \tag{323}$$

Distortion-Rate Function

• Mutual information and average distortion considering independence of the components U_i

$$I_N(g_N^Q) = \sum_{i=0}^{N-1} I_1(g_i^Q) \quad \text{and} \quad \delta_N(g_N^Q) = \frac{1}{N} \sum_{i=0}^{N-1} \delta_1(g_i^Q) \quad (324)$$

• *N*-th order distortion rate function $D_N(R)$

$$D_N(R) = \frac{1}{N} \sum_{i=0}^{N-1} D_i(R_i) \quad \text{with} \quad R = \frac{1}{N} \sum_{i=0}^{N-1} R_i \quad (325)$$

• $D_i(R_i)$: Distortion-rate function for Gaussian iid processes for component U_i

$$D_i(R_i) = \sigma_i^2 \, 2^{-2R_i} = \xi_i^{(N)} \, 2^{-2R_i} \tag{326}$$

with $\xi_i^{(N)}$ being the eigenvalues of $oldsymbol{C}_N$

Optimal Bit Allocation

• Have to distribute the bit rate in an optimal way

$$\min_{R_0, R_1, \dots, R_{N-1}} D_N(R) = \frac{1}{N} \sum_{i=0}^{N-1} \xi_i^{(N)} \, 2^{-2R_i} \qquad \text{such that} \qquad R \ge \frac{1}{N} \sum_{i=0}^{N-1} R_i$$

• Comparison on different types of mean computations

$$D_N(R) = \frac{1}{N} \sum_{i=0}^{N-1} \xi_i^{(N)} 2^{-2R_i} \ge \left(\prod_{i=0}^{N-1} \xi_i^{(N)} 2^{-2R_i}\right)^{\frac{1}{N}} = \underbrace{\left(\prod_{i=0}^{N-1} \xi_i^{(N)}\right)^{\frac{1}{N}}}_{=|\boldsymbol{C}_N|^{\frac{1}{N}} = \tilde{\xi}^{(N)}} 2^{-2R}$$

with
$$\prod_{i=0}^{N-1} 2^{-2R_i} = 2^{-2R_0} \cdot 2^{-2R_1} \cdots 2^{-2R_{N-1}} = 2^{-\sum_{i=0}^{N-1} 2R_i} = 2^{-2RN}$$

• Expression on the right-hand side of above inequality is constant: equality achieved when all terms $\xi_i^{(N)} 2^{-2R_i} = \tilde{\xi}^{(N)} 2^{-2R}$

$$R_{i} = R + \frac{1}{2} \log_{2} \frac{\xi_{i}^{(N)}}{\tilde{\xi}^{(N)}} = \frac{1}{2} \log_{2} \frac{\xi_{i}^{(N)}}{\tilde{\xi}^{(N)} 2^{-2R}} \qquad \text{with} \qquad \tilde{\xi}^{(N)} = \left(\prod_{i=0}^{N-1} \xi_{i}^{(N)}\right)^{\bar{n}}$$

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Condition for Partial Bit Rates

• So far, we have ignored that R_i cannot be less than 0

$$R_{i} = \frac{1}{2} \log_{2} \frac{\xi_{i}^{(N)}}{\tilde{\xi}^{(N)} 2^{-2R}} \ge 0 \implies R_{i} = 0 \quad \text{if} \quad \xi_{i}^{(N)} \le \tilde{\xi}^{(N)} 2^{-2R} \quad (327)$$

• Introducing the parameter $\theta,$ with $0 \leq \theta \leq D,$ yields

$$R_{i} = \begin{cases} \frac{1}{2} \log_{2} \frac{\xi_{i}^{(N)}}{\theta} & : \theta \leq \xi_{i}^{(N)} \\ 0 & : \theta > \xi_{i}^{(N)} \end{cases}$$
(328)

and

$$D_{i} = \begin{cases} \theta : \theta \leq \xi_{i}^{(N)} \\ \xi_{i}^{(N)} : \theta > \xi_{i}^{(N)} \end{cases}$$
(329)

• Can also be written as

$$R_i(\theta) = \max\left(0, \frac{1}{2}\log_2\frac{\xi_i^{(N)}}{\theta}\right) \quad \text{and} \quad D_i(\theta) = \min\left(\xi_i^{(N)}, \theta\right)$$
(330)

• This rate allocation concept is also referred to as reverse water filling

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Reverse Water Filling for Independents Gaussian RV



- Optimal rate allocation for independent Gaussian RV and MSE distortion
- Code random variable with $\sigma_i^2 > \theta$ so that the same distortion is obtained
- Do not assign any rate to random variables with $\sigma_i^2 \leq heta$
N-th Order Rate-Distortion Function

• *N*-th order distortion-rate function $D_N(R)$

$$D_N(R) = \frac{1}{N} \sum_{i=0}^{N-1} D_i(R_i) \quad \text{with} \quad R = \frac{1}{N} \sum_{i=0}^{N-1} R_i \quad (331)$$

Optimal rate allocation

$$R_i(\theta) = \max\left(0, \frac{1}{2}\log_2\frac{\xi_i^{(N)}}{\theta}\right) \quad \text{and} \quad D_i(\theta) = \min\left(\xi_i^{(N)}, \theta\right)$$
(332)

• Parametric expressions for N-th order rate-distortion function

$$D_N(\theta) = \frac{1}{N} \sum_{i=0}^{N-1} D_i = \frac{1}{N} \sum_{i=0}^{N-1} \min\left(\xi_i^{(N)}, \theta\right)$$
(333)

$$R_N(\theta) = \frac{1}{N} \sum_{i=0}^{N-1} R_i = \frac{1}{N} \sum_{i=0}^{N-1} \max\left(0, \frac{1}{2} \log_2 \frac{\xi_i^{(N)}}{\theta}\right)$$
(334)

Parametric Rate-Distortion Function

 $\bullet\,$ Rate-distortion function is given by limit for $N\to\infty$

$$D(\theta) = \lim_{N \to \infty} D_N(\theta) = \lim_{N \to \infty} \frac{1}{N} \sum_{i=0}^{N-1} \min\left(\xi_i^{(N)}, \theta\right)$$
(335)

$$R(\theta) = \lim_{N \to \infty} R_N(\theta) = \lim_{N \to \infty} \frac{1}{N} \sum_{i=0}^{N-1} \max\left(0, \frac{1}{2} \log_2 \frac{\xi_i^{(N)}}{\theta}\right)$$
(336)

• Recall: Grenander and Szegös theorem for infinite Toeplitz matrices

$$\lim_{N \to \infty} \frac{1}{N} \sum_{i=0}^{N-1} G(\xi_i^{(N)}) = \frac{1}{2\pi} \int_{-\pi}^{\pi} G(\Phi(\omega)) d\omega$$
(337)

 \implies Rate-distortion function R(D) for Gaussian sources with memory

$$D(\theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \min\{\Phi_{SS}(\omega), \theta\} d\omega$$

$$R(\theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \max\left\{0, \frac{1}{2}\log_2\frac{\Phi_{SS}(\omega)}{\theta}\right\} d\omega$$
(338)

 \implies Specifies upper bound for R(D) of all processes with the same $\Phi_{SS}(\omega)$

Illustration of Minimization Approach



Similar to reverse water filling

- At each frequency, the variance of the frequency component as given by the spectral density $\Phi_{SS}(\omega)$ is compared to the parameter θ , which represents the target mean squared error of that frequency component
- When $\Phi_{SS}(\omega)$ is found to be larger than θ , the rate $\frac{1}{2}\log_2 \frac{\Phi_{ss}(\omega)}{\theta}$ is assigned, otherwise zero rate is assigned to that frequency component

Rate-Distortion Function for Gauss-Markov Sources

• R(D) for zero-mean Gauss-Markov process with $|\rho|<1$ and variance σ^2

$$S_n = Z_n + \rho \cdot S_{n-1} \tag{339}$$

• Auto-correlation function and spectral density function are given as

$$\phi[k] = \sigma^2 |\rho|^k \qquad \Phi(\omega) = \sum_{k=-\infty}^{\infty} \phi[k] e^{-jk\omega} = \frac{\sigma^2 (1-\rho^2)}{1-2\rho \cos \omega + \rho^2} \qquad (340)$$

If we choose

$$\theta \ge \min_{\forall \omega} \Phi_{SS}(\omega) = \sigma^2 \frac{1 - \rho^2}{1 - 2\rho + \rho^2} = \sigma^2 \frac{1 - \rho}{1 + \rho}$$
(341)

we obtain

$$R(D) = \frac{1}{2}\log_2 \frac{\sigma^2(1-\rho^2)}{D}$$
(342)

Rate-Distortion Function for Gauss-Markov Sources

 \bullet Corresponding distortion rate function for $R \geq \log_2(1+\rho)$ is given by

$$D(R) = (1 - \rho^2) \cdot \sigma^2 \cdot 2^{-2R}$$
(343)

• Includes result for Gaussian iid sources ($\rho=0)$



Chapter Summary

Rate-distortion theory

- $\bullet\,$ Determine minimum rate R for a given distortion D and source
- $\bullet\,$ Determine minimum distortion D for a given distortion R and source

Operational rate-distortion function

• Fundamental bound as minimum over all possible source codes

Information rate-distortion function

- \bullet Minimum over all conditional pdfs $g_{S'|S}(s'|s)$
- Coincides with operational rate-distortion function
- Use term rate-distortion function R(D) for both
- Fundamental bound for lossless coding is given by ${\cal R}(0)$
- Discrete sources: R(D) is a convex function with $R(0) = \bar{H}(S)$
- $\bullet\,$ Continuous sources: R(D) is a convex function with $R(0)\to\infty$
- MSE distortion measure: $D(0)=\sigma^2$

Chapter Summary

Shannon lower bound

- Lower bound of rate-distortion function
- Asymptotically tight for high rates
- Suitable reference for performance evaluation at high rates
- Shannon lower bound $R_L(D)$ can often be computed analytically
- Computed $R_L(D)$ for several iid sources and Gaussian source with memory

Rate-distortion function for Gaussian sources and MSE distortion

- $\bullet \ R(D)$ for Gaussian iid sources coincides with Shannon lower bound
- Any other source than the Gaussian iid source with the same variance requires less bits for same MSE distortion
- R(D) for Gaussian source with memory can be specified as parametric expression using the power spectral density $\Phi_{SS}(\omega)$
- Derived analytic expression for Gauss-Markov source and $R \ge \log_2(1+\rho)$
- R(D) for Gaussian source with memory and a spectral density $\Phi_{SS}(\omega)$ specifies an upper bound for all other sources with the same spectral density
- \Rightarrow Gaussian sources are the most difficult to code

A fair die is rolled at the same time as a fair coin is tossed. Let A be the number on the upper surface of the die and let B describe the outcome of the coin toss, where B is equal to 1 if the result is "head" and it is equal to 0 if the result if "tail". The random variables X and Y are given by X = A + B and Y = A - B, respectively.

Calculate:

- the joint entropy H(X, Y),
- the marginal entropies H(X) and H(Y),
- the conditional entropies H(X|Y) and H(Y|X),
- the mutual information I(X;Y).

Consider a stationary Gauss-Markov process $\mathbf{X} = \{X_n\}$ with mean μ , variance σ^2 , and the correlation coefficient ρ (correlation coefficient between two successive random variables).

Determine the mutual information $I(X_k; X_{k+N})$ between two random variables X_k and X_{k+N} , where the distance between the random variables is N times the sampling interval.

Interpret the results for the special cases $\rho=-1,~\rho=0,$ and $\rho=1.$

Hint: In the lecture, we showed

$$E\left\{ (\mathbf{X} - \mu_N)^{\mathrm{T}} \cdot \mathbf{C}_N^{-1} \cdot (\mathbf{X} - \mu_N) \right\} = N,$$

which can be useful for the problem.

Show that for discrete random processes the fundamental bound for lossless coding is a special case of the fundamental bound for lossy coding.

Determine the Shannon lower bound with MSE distortion, as distortion-rate function, for iid processes with the following pdfs:

- The exponential pdf $f_E(x) = \lambda \cdot e^{-\lambda \cdot x}$, with $x \ge 0$
- \bullet The zero-mean Laplace pdf $f_L(x) = \frac{\lambda}{2} \cdot e^{-\lambda \cdot |x|}$

Express the distortion-rate function for the Shannon lower bound as a function of the variance $\sigma^2.$

Which of the given pdfs is easier to code (if the variance is the same)?